

Digital Image Restoration

Ankita Patil^{#1}, Sumedha Devasthali^{#2}, Seema Gujar^{#3} Nikita Jadhav^{#4}

[#]Information technology Department, Atharva college of Engineering,
Malad (w), Mumbai-400095, Maharashtra, India

patilankita770@yahoo.com
devasthali.sumedha@gmail.com
seemagujar1992@gmail.com
Nj.ms1991@gmail.com

Abstract – Image restoration is the operation of taking a corrupted/noisy image and estimating the clean and original image. Image restoration is an important issue in high-level image processing. Images are often degraded during the data acquisition process. It also includes the process that attempts to remove degradation and restore an image to its previous state.

It is used in various fields such as photography image, satellite image, medical image, astronomical image, remote sensing, microscopy imaging, etc.

In this paper, we compare the three image restoration techniques: namely inverse filter, Wiener filter, and Lucy-Richardson algorithm.

Keywords- Peak Signal to noise ratio, Image Restoration, Degradation model, Richardson-Lucy algorithm, Wiener Filter, inverse filter

i. INTRODUCTION

Images are used for storing useful information but in many times while capturing the image or while acquiring the image some distortion is appearing in the image so the image we get is a distorted image, the stored image is the degraded version of the original scene. The different degradations, which come into the image are noise, geometrical degradations, color imperfections, and blur [1]. Blurring is a unsharp image area it can be caused by relative motion between the camera and the original scene for e.g. if we want to capture the moving object with the camera in that case because of the movement of the camera it is possible that the image that is captured will be blurred which is known as motion blur. There are many other situations if the camera is not focused properly then also the image is blurred. In addition to these blurring effects, noise always corrupts any recorded image [8]. Noise is any undesired information that spoils an image. Digital image noise arises during the acquisition and transmission process. There are various types of noise in image processing: Gaussian noise, Rayleigh noise, Gamma noise, exponential noise, salt and pepper noise, periodic noise, etc. In the use of image restoration methods to restore blurred and noisy images. Also, it aims at finding out the causes of image degradation and eliminating them to a maximum possible level.

A. Degradation Model

In the real world it is very difficult to get the exact image. In case of photography or imaging systems these are caused by emulsion, motion blur, and camera focus problems. In Fig. 1, the degradation process is shown. The input image $f(x, y)$ is degraded by the degradation function H , which is operated on $f(x, y)$. After the addition of noise $n(x, y)$, $g(x, y)$ gives the degraded image which we want to recover the input image $f(x, y)$ using an image restoration filter. After applying restoration filters we obtain the restored image $\hat{f}(x, y)$. [7]

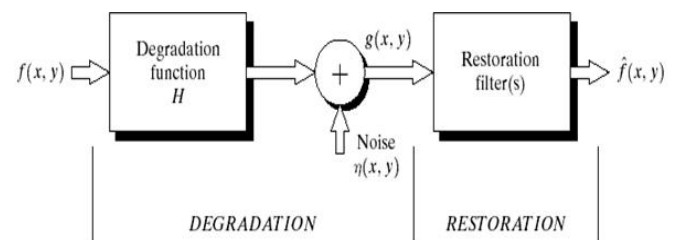


Fig: 1(a) Degradation Model

B. Blurring

This blurring may occur because of various reasons. Maybe, the camera setting is not proper or the lens is not focused properly. So, that leads to one kind of blurring. The other kind of blurring can be if we take a picture from a moving platform; say for example, from a moving car or from a moving train. In that case also you might have observed that the image that you get is not a clear image.

C. Blurring Types:-

In digital images there are 4 common types of blur effects:

- 1) Average Blur
- 2) Gaussian Blur
- 3) Motion Blur
- 4) Out of Focus Blur

ii. RELATED WORK

Image restoration used to recover or try to restore image which has been degraded by some knowledge of degradation method. It is widely used in various fields of applications, such as medical imaging, astronomical imaging, remote sensing, microscopy imaging, photography deblurring, and forensic science, etc. Often the benefits of improving image quality to the maximum possible extent for outweigh the cost and complexity of the restoration algorithms involved. We are going to implement three image restoration techniques namely inverse filter, Wiener filter and Lucy Richardson algorithm. Inverse filter is used to restore images which are degraded due to environmental conditions such as atmospheric turbulence. The main drawback of this filter is its incapability to handle noise. This is overcome by using the Wiener filtering technique. As it is known that inverse filtering is incapable of handling noise we use the Wiener filtering technique. It performs image restoration by combining the degradation function and statistical characteristics of noise. Lucy Richardson algorithm is a convolution algorithm which follows an iterative procedure for the recovery of the blurred image.

iii. CLASSIFICATION TECHNIQUES

For image restoration 3 techniques are used here to restore the image using SNR.

Techniques are

- Inverse filter
- Wiener filter
- Lucy Richardson Algo

A. Inverse filter

If we create a good model of the blurring function that corrupted an image, the quickest and easiest way to restore that is by inverse filtering. Unfortunately, since the inverse filter is a form of high pass filter, inverse filtering responds very badly to any noise that is present in the image because noise tends to be high frequency

F, G, N, H are in 2D-DFT domain.

$G(x,y)=F(x,y)H(x,y)+N(x,y)$ where $F(x,y)$ is the 2D-FT of an input image $f(x,y)$, $N(x,y)$ is a white noise with zero mean and unit variance, and $H(x,y)$ is a degradation function which is given by

$$H(x, y)=\exp [-K(x^2+y^2)^{5/6}] \quad (1)$$

2D-IFT of $G(x,y)$ is the blurred image (item 2 above) and is the output of inverse filter

B. Wiener Filter

The inverse filtering is a restoration technique for deconvolution, i.e., when the image is blurred by a known low pass filter, it is possible to recover the image by inverse

Filtering or generalized inverse filtering. However, inverse filtering is very sensitive to additive noise. The approach of Reducing one degradation at a time allows us to develop a restoration algorithm for each type of degradation and simply combine them. The Wiener filtering executes an optimal tradeoff between inverse filtering and noise smoothing. It removes the additive noise and inverts the blurring simultaneously

For Wiener Filter

$$G(f_1, f_2) = \frac{H^*(f_1, f_2) S_{uu}(f_1, f_2)}{|H(f_1, f_2)|^2 S_{uu}(f_1, f_2) + S_{nn}(f_1, f_2)} \quad (2)$$

C. Lucy- Richardson Algorithm Technique[5]

The Lucy-Richardson algorithm is an iterative technique originally used for the restoration of astronomical images in the presence of Poisson noise it is an iterative procedure in which the pixels of the observed image are represented using the PSF and the latent image as follows:

$$D_i = \sum p_{ij} u_j \quad (3)$$

where p_{ij} is the point spread function (the fraction of light coming from true location j that is observed at position i), u_j is the pixel value at location j in the latent image, and d_i is the observed value at pixel location i . The statistics are performed under the assumption that u_j are Poisson distributed, which is appropriate for photon noise in the data.

The basic idea is to calculate the most likely u_j given the observed d_i and known p_{ij} . This leads to an equation for u_j which can be solved iteratively according to

$$u_j^{(t+1)} = u_j^{(t)} \sum_i \frac{d_i}{c_i} p_{ij} \quad (4)$$

Where

$$c_i = \sum_j p_{ij} u_j^{(t)}. \quad (5)$$

It has been shown empirically that if this iteration converges, it converges to the maximum likelihood solution for u_j

iv. EXPERIMENTAL RESULT



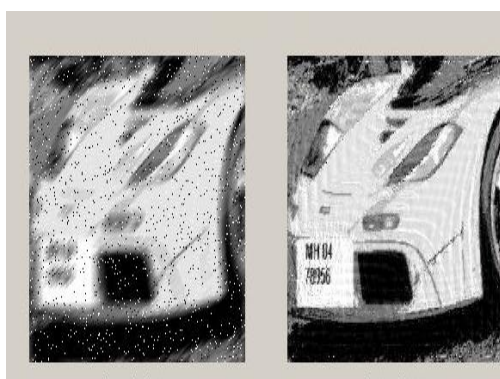
(a)

(b)



(c)

(d)



(e)

(f)

Fig: 4(a) Degraded Image (b) Image after Lucy Richardson algorithm (c) Degraded Image (d) Image after Inverse Filtering (e) Degraded Image (f) Image after wiener Filter

To find SNR:

SNR	Angle	Length	Image Restoration Techniques		
			Lucy	Inverse	Wiener
10	45	6	11.8423	12.8899	14.5264
30	45	6	11.8441	12.8512	14.5329
50	45	6	11.8449	12.9172	14.5339

v. CONCLUSION

In this paper, this is going to implement the comparison between the three algorithms for searching better restoration technique. The Lucy Richardson that provide better restoration based on as compare to Inverse filter and Wiener filter

vi. FUTURE SCOPE

A digital image is a noisy realization of a scene. The SNR is limited by the quantum nature of light. The resolution is degraded by the finite lens aperture of the imaging system due to wave description of light.

Image restoration aims at:

A) Improving the image resolution beyond the systems bandwidth.

B) Improving the peak signal to noise ratio.

The purpose of image restoration is to produce the best estimate of the source image, given the recorded data and some apriori knowledge. Restoration allows recovery of the image, removing noise, enhancing brightness, color and details.

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